

Estimation and prediction in
generalized linear latent and mixed models:
A practical perspective

Anders Skrondal
Division of Epidemiology
Norwegian Institute of Public Health

Slide 1

joint work with
Sophia Rabe-Hesketh (King's College London)
and Andrew Pickles (The University of Manchester)

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OUTLINE

Slide 2

- I.** A general model framework for latent variable modelling:
Generalised Linear Latent And Mixed Models (GLLAMM)
- II.** Estimation methods: When do they work and fail?
 - Methods assuming normal latent variables
 - Marginal and Penalized Quasi-Likelihood
 - Maximum Likelihood
 - * Gaussian quadrature
 - * Adaptive quadrature
 - Non-Parametric Maximum Likelihood
- III.** Prediction methods for latent variables: When do they work and fail?
 - Empirical Bayes assuming normal latent variables
 - Empirical Bayes based on non-parametric maximum likelihood
- IV.** Conclusion

Slide 3

I. GLLAMM

- Response model: Generalised linear model conditional on latent variables
 - Linear predictor: latent variables as factors or random coefficients
 - Links and distributions
- Structural model
 - Regressions of latent variables on observed variables
 - Regressions of latent variables on other latent variables
- Distribution of the latent variables (disturbances)
 - Multivariate normal
 - Discrete

Slide 4

GLLAMM: Links and families

- The conditional expectation of the response is 'linked' to the linear predictor

$$g(E[y|\mathbf{x}, \boldsymbol{\eta}, \mathbf{z}]) = \nu$$

- The conditional distribution of the response is from the exponential family:

Links
identity
reciprocal
logarithm
logit
probit
scaled probit
compl. log-log

Families
Gaussian
gamma
Poisson
binomial

Ordinal responses
ordinal logit
ordinal probit
ordinal compl. log-log
scaled ord. probit

Nominal & Rankings
multinomial logit

- Heteroscedasticity: Dispersion or scale parameters can be modelled as $\log \sigma = \mathbf{z}^{(1)\prime} \boldsymbol{\alpha}$

Slide 5

GLLAMM: Linear Predictor

$$\nu = \mathbf{x}'\boldsymbol{\beta} + \sum_{l=2}^L \sum_{m=1}^{M_l} \eta_m^{(l)} \mathbf{z}_m^{(l)'} \boldsymbol{\lambda}_m^{(l)} \quad \text{for identification, } \lambda_{m1}^{(l)} = 1$$

- Fixed part: $\mathbf{x}'\boldsymbol{\beta}$ as usual
- Random part:
 - $\eta_m^{(l)}$ is m th latent variable at level l , $m = 1, \dots, M_l$,
 $l = 2, \dots, L$
 - $\eta_m^{(l)}$ can be a **factor** or a **random coefficient**
 - $\mathbf{z}_m^{(l)}$ are variables and $\boldsymbol{\lambda}_m^{(l)}$ are parameters

Slide 6

Random coefficient models in GLLAMM

- One covariate multiplies each latent variable,
$$\eta_m^{(l)} z_m^{(l)} \quad (\lambda_m^{(l)} = 1)$$
- e.g. Latent growth curve model for individuals j (level 2)
observed at times t_{ij} , $i = 1, \dots, n_j$ (level 1)

$$\nu_{ij} = \beta_1 + \beta_2 t_{ij} + \eta_{1j}^{(2)} + \eta_{2j}^{(2)} t_{ij}$$

β_1, β_2 : mean intercept and slope

$\eta_{1j}^{(2)}, \eta_{2j}^{(2)}$: random deviations of the subject-specific intercepts
and slopes from their means

Factor models in GLLAMM

- A linear combination of dummy variables for the items multiplies each latent variable,

$$\eta_m^{(l)} \mathbf{z}_m^{(l)'} \boldsymbol{\lambda}_m^{(l)}$$

- e.g. One-factor model for items i , $i = 1, \dots, I$ (level 1) and subjects j (level 2)

$$\begin{aligned} \nu_{ij} &= \beta_1 \delta_{1i} + \dots + \beta_I \delta_{Ii} + \eta_j^{(2)} (\delta_{1i} + \lambda_2^{(2)} \delta_{2i} \dots + \lambda_I^{(2)} \delta_{Ii}) \\ &= \beta_i + \eta_j^{(2)} \lambda_i^{(2)}, \end{aligned}$$

where

$$\delta_{pi} = \begin{cases} 1 & \text{if } p = i \\ 0 & \text{otherwise} \end{cases}$$

β_i : intercept for item i

$\eta_j^{(2)}$: common factor

$\lambda_i^{(2)}$: factor loading for item i , $\lambda_1^{(2)} = 1$

unit j	item i	δ_{1i}	δ_{2i}	\dots	δ_{Ii}	y_{ij}
1	1	1	0	\dots	0	y_{11}
1	2	0	1	\dots	0	y_{21}
\vdots	\vdots	\vdots	\vdots	\ddots	\vdots	\vdots
1	I	0	0	\dots	1	y_{I1}

Slide 7

GLLAMM: Structural model

- Regressions of latent variables on other latent and explanatory variables

$$\boldsymbol{\eta} = \mathbf{B}\boldsymbol{\eta} + \boldsymbol{\Gamma}\mathbf{w} + \boldsymbol{\zeta}$$

- $\boldsymbol{\eta} = (\eta_1^{(2)}, \eta_2^{(2)}, \dots, \eta_{M_2}^{(2)}, \dots, \eta_1^{(l)}, \dots, \eta_{M_l}^{(l)}, \dots, \eta_{M_L}^{(L)})'$ (M elements)

– factors

– random coefficients

- \mathbf{B} is an upper diagonal $M \times M$ matrix of regression coefficients
- $\boldsymbol{\Gamma}$ is an $M \times p$ matrix of regression coefficients
- \mathbf{w} is a p dimensional vector of explanatory variables
- $\boldsymbol{\zeta}$ is an M dimensional vector of errors/disturbances (same level as corresponding elements in $\boldsymbol{\eta}$)

Slide 8

Slide 9

GLLAMM: Latent variable distributions

- Multivariate normal disturbances $\zeta^{(l)}$ with covariance matrices $\Psi^{(l)}$, independent across levels
- Discrete
 - Mixture model
 - * latent class model
 - * latent profile model
 - Nonparametric estimator of a continuous, discrete or mixed distribution

Slide 10

II. ESTIMATION METHODS FOR GLMM'S

- Marginal Quasi Likelihood (MQL) and Penalized Quasi Likelihood (PQL)
- Maximum Likelihood (ML)
 - Gaussian Quadrature (GQ)
 - Adaptive Quadrature (AQ)
- Non-Parametric Maximum Likelihood (NPML)
- Markov Chain Monte Carlo (MCMC)
[Will not cover MCMC in this talk!]

For simplicity: Random intercept model

- Linear predictor:

- Two-level random intercept model (unit i , cluster j)

$$\nu_{ij} = \mathbf{x}'_{ij}\boldsymbol{\beta} + \zeta_j^{(2)}, \quad \zeta_j^{(2)} \sim N(0, \psi^{(2)})$$

- Three-level model random intercept model (unit i , cluster j , supercluster k)

$$\nu_{ijk} = \mathbf{x}'_{ijk}\boldsymbol{\beta} + \zeta_{jk}^{(2)} + \zeta_k^{(3)}, \quad \zeta_{jk}^{(2)} \sim N(0, \psi^{(2)}), \zeta_k^{(3)} \sim N(0, \psi^{(3)})$$

Slide 11

- Latent response formulation for dichotomous observed responses:

- Threshold model:

$$y_{ijk}^* = \nu_{ijk} + \epsilon_{ijk},$$

$$y_{ijk} = \begin{cases} 1 & \text{if } y_{ijk}^* > 0 \\ 0 & \text{if } y_{ijk}^* \leq 0 \end{cases}$$

- Type of model:

- * LOGIT random intercept model if $\epsilon_{ijk} \sim \text{Logistic}$,

$$\text{var}(\epsilon_{ijk}) = \pi^2/3$$

- * PROBIT random intercept model if $\epsilon_{ijk} \sim N(0, 1)$

Intra-class correlation

- Intra-class correlations for latent responses

- Two-level logit random intercept model

$$\rho = \text{cor}(y_{ij}^*, y_{i'j}^* | \mathbf{x}_{ij}) = \frac{\psi^{(2)}}{\psi^{(2)} + \pi^2/3}$$

- Three-level logit random intercept model

$$\rho_a = \text{cor}(y_{ijk}^*, y_{i'jk}^* | \mathbf{x}_{ijk}) = \frac{\psi^{(2)} + \psi^{(3)}}{\psi^{(2)} + \psi^{(3)} + \pi^2/3}$$

$$\rho_b = \text{cor}(y_{ijk}^*, y_{i'jk}^* | \mathbf{x}_{ijk}, \zeta_k^{(3)}) = \frac{\psi^{(2)}}{\psi^{(2)} + \pi^2/3}$$

$$\rho_c = \text{cor}(y_{ijk}^*, y_{i'jk}^* | \mathbf{x}_{ijk}) = \frac{\psi^{(3)}}{\psi^{(2)} + \psi^{(3)} + \pi^2/3}$$

Slide 12

- Designing simulations:

Relation between $\psi^{(2)}$ and ρ in two-level model

$\psi^{(2)}$	0.01	0.10	0.50	1	2	4	10	20
logit: ρ	0.00	0.03	0.13	0.23	0.38	0.55	0.75	0.86
probit: ρ	0.01	0.09	0.33	0.50	0.67	0.80	0.91	0.95

MQL and PQL: Approximate linear mixed models

- Conditional expectation of the response in generalized linear mixed models

$$\mu_{ij} = h(\nu_{ij}),$$

where $h(\cdot)$ is the inverse link function.

- Linearize by expanding $h(\nu_{ij})$ as a **1st order** Taylor series around the 'current' value of the linear predictor

$$\bar{\nu}_{ij} = \mathbf{x}'_{ij}\hat{\boldsymbol{\beta}} + \tilde{\zeta}_j^{(2)}$$

$$\begin{aligned} y_{ij} &\approx h(\bar{\nu}_{ij}) + \mathbf{x}'_{ij}(\boldsymbol{\beta} - \hat{\boldsymbol{\beta}})h'(\bar{\nu}_{ij}) \\ &\quad + (\zeta_j^{(2)} - \tilde{\zeta}_j^{(2)})h'(\bar{\nu}_{ij}) \\ &\quad + \epsilon_{ij}, \end{aligned}$$

where ϵ_{ij} is a heteroscedastic error term with variance $\phi V(\bar{\mu}_{ij})$ corresponding to the chosen distribution

(e.g. Schall, 1991; Goldstein, 1991; Wolfinger, 1993; Breslow and Clayton, 1993; McGilchrist, 1994)

- Reformulate as approximate linear mixed model

$$\underbrace{y_{ij} - \omega_{ij}}_{v_{ij}^*} \approx \underbrace{\mathbf{x}'_{ij}h'(\bar{\nu}_{ij})\boldsymbol{\beta}}_{\mathbf{x}'_{ij}\boldsymbol{\beta}} + \underbrace{\zeta_j^{(2)}h'(\bar{\nu}_{ij})}_{\zeta_j^{(2)}} + \epsilon_{ij},$$

with offset $\omega_{ij} = h(\bar{\nu}_{ij}) - (\mathbf{x}'_{ij}\hat{\boldsymbol{\beta}} + \tilde{\zeta}_j^{(2)})h'(\bar{\nu}_{ij})$.

- Estimate as if linear mixed model

Slide 13

MQL and PQL cont'd

- Extend Taylor expansion to **2nd order** for the random part (e.g. Goldstein, 1995; Goldstein and Rasbash, 1996)

$$\begin{aligned} y_i &\approx h(\bar{\nu}_{ij}) + \mathbf{x}'_{ij}(\boldsymbol{\beta} - \hat{\boldsymbol{\beta}})h'(\bar{\nu}_{ij}) \\ &\quad + (\zeta_j^{(2)} - \tilde{\zeta}_j^{(2)})h'(\bar{\nu}_{ij}) \\ &\quad + \underbrace{\frac{1}{2}(\zeta_j^{(2)} - \tilde{\zeta}_j^{(2)})^2 h''(\bar{\nu}_{ij})}_{\text{second order}} \\ &\quad + \epsilon_{ij}. \end{aligned}$$

- Types of estimators:

	1st order	2nd order
$\tilde{\zeta}_j^{(2)} = 0$	MQL-1	MQL-2
$\tilde{\zeta}_j^{(2)} \approx \text{EB}$	PQL-1	PQL-2

- PQL better approximation than MQL and second order expansions of the random part improve on first order
- Software:
 - HLM (also higher order Laplace for two-level models)
 - MLwiN (also bias-correcting bootstrap)

Slide 14

Slide 15

Performance of MQL & PQL

- Pros:
 - Computationally efficient
 - Perform well when posterior is close to normal:
 - * Conditional distribution of responses given random effects close to normal
 - Poisson distribution with mean 7 or greater
(e.g. McCullagh and Searle, 2001)
 - Proportions with large binomial denominators
 - * Large cluster size
- Cons:
 - Downward bias of fixed effects, random effect variances and their standard errors for
 - * Dichotomous data with small cluster sizes
(e.g. Rodriguez and Goldman, 1995, 2001; Breslow and Lin, 1995; Lin and Breslow, 1995; Goldstein and Rasbash, 1996; Browne and Draper, 2002)
 - * 'Large' variance components
 - No likelihood!
 - Difficult to assess performance for a given application

Slide 16

Misbehaviour of MQL & PQL: Simulation

- 500 datasets simulated to have the same structure as data from the 1987 Guatemalan National Survey of Maternal and Child Health (Browne and Draper, 2002)
- Outcome: whether women received prenatal care or not
- Simulated 2449 births i (level 1) by 1558 women j (level 2) from 161 communities k (level 3) from a three-level logit random intercept model with one covariate at each level:

$$\eta_{ijk} = \beta_0 + \beta_1 x_{1ijk} + \beta_2 x_{2jk} + \beta_3 x_{3k} + \zeta_{jk}^{(2)} + \zeta_k^{(3)}$$

	True	Estimate		Coverage 95%CI	
		MQL-1	PQL-2	MQL-1	PQL-2
β_0	0.65	0.47	0.61	77	92
β_1	1.0	0.74	0.95	69	96
β_2	1.0	0.75	0.96	18	91
β_3	1.0	0.73	0.94	70	90
$\psi^{(2)}$	1.0	0.03	0.57	0	27
$\psi^{(3)}$	1.0	0.55	0.89	2	78

$$\rho_a = 0.38, \rho_b = 0.23 \text{ and } \rho_c = 0.19.$$

Gaussian Quadrature (GQ)

- Exploit conditional independence of responses given latent variables

$$f(y_{1j} \cap \dots \cap y_{n_j j} | \zeta_j^{(2)}; \boldsymbol{\beta}, \boldsymbol{\lambda}) = \prod_i f(y_{ij} | \zeta_j^{(2)}; \boldsymbol{\beta}, \boldsymbol{\lambda})$$

- 'Marginal' likelihood contribution

$$\ell_j(\boldsymbol{\beta}, \boldsymbol{\lambda}, \psi) = \int \phi(\zeta_j^{(2)}; 0, \psi) \prod_i f(y_{ij} | \zeta_j^{(2)}; \boldsymbol{\beta}, \boldsymbol{\lambda}) d\zeta_j^{(2)}$$

- Change of variable [$u_j = \zeta_j^{(2)} / \sqrt{\psi}$]

$$\ell_j(\boldsymbol{\beta}, \boldsymbol{\lambda}, \psi) = \int \phi(u_j) \prod_i f(y_{ij} | \sqrt{\psi} u_j) du_j$$

- Gaussian quadrature approximation

(e.g. Bock & Lieberman, 1970; Butler and Moffitt, 1982)

$$\ell_j(\boldsymbol{\beta}, \boldsymbol{\lambda}, \psi) \approx \sum_{r=1}^R W_r \prod_i f(y_{ij} | \sqrt{\psi} A_r),$$

- $r = 1, \dots, R$ quadrature points
- W_r quadrature weights
- A_r locations

- Approximation exact if $\prod_i f(y_{ij} | \sqrt{\psi} u_j)$ were a $(2R - 1)$ th polynomial in u_j

- Software: aML, gllamm, MIXOR(etc.)

Slide 17

Performance of GQ

- Pros:

- Works well for dichotomous responses with small to moderate cluster sizes, precisely where MQL/PQL fails (e.g. Rodriguez and Goldman, 2001; Stryhn et al., 2000; Rabe-Hesketh et al., 2001).
- Performance easily assessed by comparing solutions with different numbers of quadrature points.

- Cons:

- Computationally intensive, particularly for many random effects. Large number of quadrature points often needed to closely approximate the likelihood (e.g. Crouch and Spiegelman, 1990)
- Problematic if the posterior distribution has a sharp peak
 - * Dichotomous responses with:
 - large cluster sizes (e.g. Lee, 2000)
 - high intraclass correlation (e.g. Lesaffre & Spiessens, 2001).
 - * Counts (conditionally Poisson distributed) (e.g. Albert and Follmann, 2000).
 - * Continuous responses (conditionally normally distributed)

Slide 18

Adaptive Quadrature (AQ)

- Reformulation of likelihood contribution

(e.g. Naylor and Smith, 1982; Liu and Pierce, 1994; Pinheiro and Bates, 1995; Rabe-Hesketh, Skrondal and Pickles, 2002)

$$\ell_j(\boldsymbol{\beta}, \boldsymbol{\lambda}, \boldsymbol{\psi}) = \int \underbrace{\phi(u_j; \mu_j, \sigma_j^2)} \left[\frac{\phi(u_j) \prod_i f(y_{ij} | \sqrt{\psi} u_j)}{\phi(u_j; \mu_j, \sigma_j^2)} \right] du_j$$

– $\phi(u_j; \mu_j, \sigma_j^2)$: normal density approximating posterior (approximately proportional to the numerator in [])

Slide 19

- Change of variable [$v_j = (u_j - \mu_j) / \sigma_j$]

$$\ell_j(\boldsymbol{\beta}, \boldsymbol{\lambda}, \boldsymbol{\psi}) = \int \frac{\phi(v_j)}{\sigma_j} \left[\frac{\phi(\sigma_j v_j + \mu_j) \prod_i f(y_{ij} | \sqrt{\psi}(\sigma_j v_j + \mu_j))}{\frac{1}{\sqrt{2\pi}\sigma_j} \exp(-v_j^2/2)} \right] \sigma_j dv_j$$

- Approximation via adaptive quadrature

$$\begin{aligned} \ell_j(\boldsymbol{\beta}, \boldsymbol{\lambda}, \boldsymbol{\psi}) &\approx \sum_{r=1}^R W_r \left[\frac{\phi(\sigma_j A_r + \mu_j) \prod_i f(y_{ij} | \sqrt{\psi}(\sigma_j A_r + \mu_j))}{\frac{1}{\sqrt{2\pi}\sigma_j} \exp(-A_r^2/2)} \right] \\ &= \sum_{r=1}^R \omega_{jr} \prod_i f(y_{ij} | \sqrt{\psi} \alpha_{jr}) \end{aligned}$$

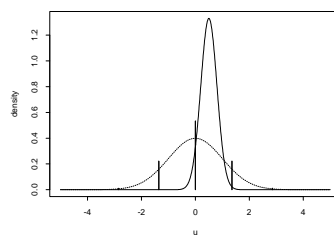
– $\alpha_{jr} = \sigma_j A_r + \mu_j$

– $\omega_{jr} = \sqrt{2\pi}\sigma_j \exp(A_r^2/2) \phi(\sigma_j A_r + \mu_j) W_r$

- Software: glamm, SAS NL MIXED (only two-level models)

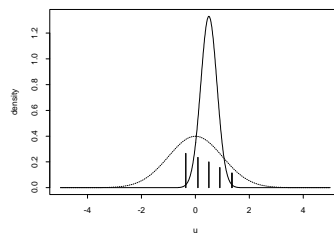
Adaptive quadrature places quadrature locations under peak of integrand

Quadrature



Slide 20

Adaptive quadrature



Prior (dotted curve) and posterior (solid curve) densities
(Integrand is proportional to posterior)

Slide 21

Performance of AQ

- Pros:
 - Works well
 - * if the posterior densities are nearly normal (e.g. large cluster sizes and/or counts.)
 - * if the posterior densities are highly non-normal and not too peaked (e.g. dichotomous responses, small cluster sizes and moderate intraclass correlation)
 - * even when the posterior densities are highly non-normal but with sharp peaks, e.g. dichotomous responses, small cluster sizes and large intraclass correlation (Rabe-Hesketh, Skrondal and Pickles, submitted)
 - Implementation in gllamm more computationally efficient than ordinary quadrature
- Cons:
 - Computationally intensive, especially for many latent variables. But: spherical rules improves efficiency (Rabe-Hesketh, Skrondal and Pickles, submitted)
 - Less computationally efficient than MQL/PQL

Slide 22

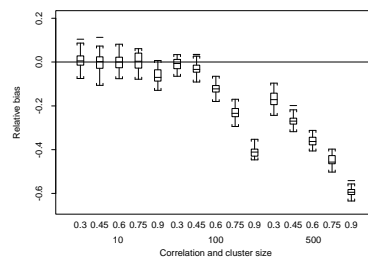
Behaviour of GQ and AQ: Simulation

100 simulations from two-level probit random intercept model

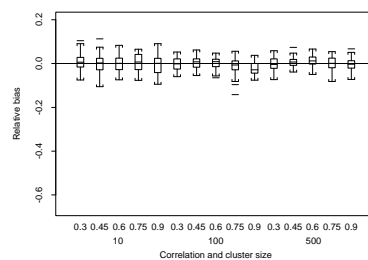
$$\eta_{ij} = \beta_0 + \beta_1 x_{1ij} + \beta_2 x_{2j} + \zeta_j^{(2)}$$

Relative bias $(\sqrt{\hat{\psi}^{(2)}} - \sqrt{\psi^{(2)}}) / \sqrt{\psi^{(2)}}$ for different intra-class correlations ρ and cluster sizes n_j .

GQ



AQ



Slide 23

Behaviour of AQ: Poisson example

- A randomized longitudinal epilepsy trial comparing a new drug with placebo. Outcomes are seizure counts y_{ij} for patient j during the two weeks before visit i . Data from Leppik et.al, 1987, analysed by e.g. Thall and Vail, 1990; Breslow and Clayton, 1993
- Covariates (Breslow and Clayton, 1993):
 - lbas: log of a quarter of number of seizures in eight week preceding entry into the trial
 - treat: dummy variable for treatment
 - lbas_trt: interaction between lbas and treat
 - v4: dummy variable for fourth visit to account for drop in seizure counts during fourth interval
- Log-linear (Poisson regression) model with a random intercept for subjects

$$\log(\mu_{ij}) = \mathbf{x}_{ij}'\boldsymbol{\beta} + \zeta_j^{(2)}.$$

(Model II in Breslow and Clayton, 1993)

Slide 24

Behaviour of AQ: Poisson example cont'd

	Model II		
	PQL-1	GQ(20)	AQ(10)
<i>Fixed effects</i>			
lbas	0.87 (0.14)	0.94 (—)	0.88 (0.13)
treat	-0.91 (0.41)	-1.42 (0.22)	-0.93 (0.40)
lbas_trt	0.33 (0.21)	0.59 (0.11)	0.34 (0.20)
lage	0.47 (0.35)	0.70 (0.30)	0.48 (0.35)
v4	-0.16 (0.05)	-0.16 (0.05)	-0.16 (0.05)
<i>Random effect</i>			
SD of intercept	0.53 (0.06)	0.51 (0.05)	0.50 (0.06)

Slide 25

Non-parametric maximum likelihood estimation NPMLE

- The likelihood contribution has the form

$$l_j(\beta, \lambda, \pi_R, \mathbf{z}_R) = \sum_{r=1}^R \pi_r \prod_i f(y_{ij} | \zeta_j^{(2)} = z_r)$$

- z_r are location parameters, π_r are mass parameters and \mathbf{z}_R , π_R are the corresponding R -dimensional parameter vectors.
- Gaussian quadrature has the same form with z_r replaced by $\sqrt{\psi}A_r$ and π_r replaced by W_r . But: crucial difference that A_r and W_r fixed apriori and not estimated.

(e.g. Aitkin, 1999; Rabe-Hesketh, Pickles and Skrondal, revised)

- NPMLE:
 - Increase number of mass-points until likelihood does not increase
 - Mass-points introduced one by one using the concept of a directional derivative
- Software: glamm

Slide 26

Example: Logistic regr. with covariate measurement error

- Problem
 - Effect of fibre intake (continuous, measured twice on a subset of subjects) on coronary heart disease (CHD present/absent) (Morris, Marr and Clayton, 1977)
- Data and notation
 - Responses are dietary fibre intake ($i=1, 2$) and coronary heart disease ($i=3$)
 - η_j is j th subject's true dietary intake
- Measurement model for fibre intake: y_{1j}, y_{2j} conditionally independently normally distributed with

$$E[y_{ij} | \eta_j] = \beta_i + \eta_j, \quad i = 1, 2 \quad (\lambda_1 = \lambda_2 = 1)$$

$$\text{var}[y_{ij} | \eta_j] = \sigma^2 \quad [\text{Measurement error variance}]$$

- Disease model: y_{i3} conditionally Bernoulli with

$$\text{logit}(E[y_{3j} | \eta_j]) = \beta_3 + \eta_j \lambda_3 \quad [\lambda_3 \text{ is log(OR)}]$$

Structural equation models

1. Solely direct effect of x on y_3

$$\text{Measurement model : } E[y_{ij}|\eta_j] = \beta_i + \eta_j, \quad j = 1, 2$$

$$\text{Disease model : } \text{logit}(E[y_{3j}|\eta_j]) = \beta_3 + \beta_4 x_j + \eta_j \lambda_3$$

2. Solely indirect effect of x on y_3

$$\eta_j = \gamma x_j + \zeta_j$$

$$\text{Measurement model : } E[y_{ij}|\eta_j] = \beta_i + \gamma x_j + \zeta_j$$

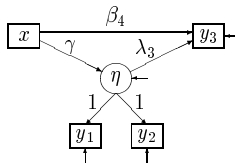
$$\text{Disease model : } \text{logit}(E[y_{3j}|\eta_j]) = \beta_3 + \gamma \lambda_3 x_j + \zeta_j \lambda_3$$

⇒ Requires nonlinear constraints or structural model

3. Both direct and indirect effects of x on y_3

$$\text{Measurement model : } E[y_{ij}|\eta_j] = \beta_i + \gamma x_j + \zeta_j$$

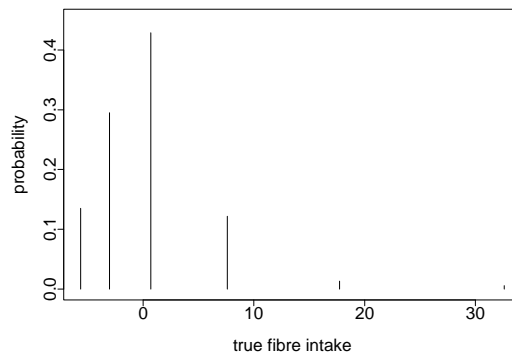
$$\text{Disease model : } \text{logit}(E[y_{3j}|\eta_j]) = \beta_3 + (\beta_4 + \gamma \lambda_3) x_j + \zeta_j \lambda_3$$



Slide 27

Normal vs. non-parametric exposure distribution

Parameters	GQ(60)		NPMLE(6)	
	Estimates	SE	Estimates	SE
λ_3	-0.13	0.05	-0.15	0.06
σ^2	6.95	1.14	6.13	0.86
$\psi^{(2)}$	23.66	0.52	24.93	—
Log-likelihood=-1372.4		Log-likelihood=-1319.8		



Slide 28

Slide 29

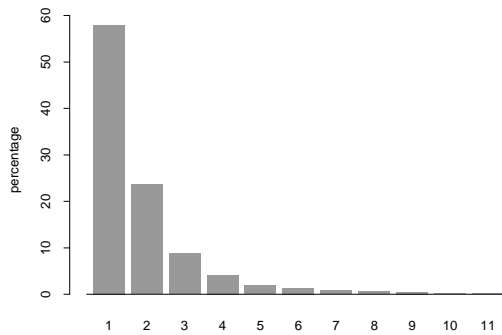
Simulation: Normal true exposure distribution

Parameter	True value	Quadrature (60 points)			
		Mean	SD	Bias	RMSE
λ_3	-0.13	-0.13	0.04	0.00	0.04
σ^2	6.86	7.04	1.08	0.18	1.09
$\psi^{(2)}$	23.81	23.35	2.64	-0.46	2.67

Parameter	True value	NPMLE			
		Mean	SD	Bias	RMSE
λ_3	-0.13	-0.13	0.04	0.00	0.04
σ^2	6.86	6.59	1.11	-0.27	1.14
$\psi^{(2)}$	23.81	23.82	2.63	0.01	2.62

Slide 30

Skewed true exposure distribution



Slide 31

Simulation: Skewed true exposure distribution

Parameter	True value	Quadrature (60 points)			
		Mean	SD	Bias	RMSE
λ_3	-0.13	-0.10	0.04	0.03	0.05
σ^2	6.86	7.06	1.13	0.20	1.14
$\psi^{(2)}$	23.81	23.00	4.83	-0.81	4.88

Parameter	True value	NPMLE			
		Mean	SD	Bias	RMSE
λ_3	-0.13	-0.14	0.08	-0.01	0.08
σ^2	6.86	6.42	0.98	-0.44	1.07
$\psi^{(2)}$	23.81	23.63	4.71	-0.18	4.69

Slide 32

III. PREDICTION OF LATENT VARIABLES

- Empirical Bayes (EB) prediction: posterior mean of latent variable given response with estimates plugged in

- Normally distributed latent variable:

- Posterior mean for unit j

$$\tilde{\zeta}_j^{\text{EB}} = E[\zeta_j | \mathbf{y}_j; \hat{\boldsymbol{\beta}}, \hat{\boldsymbol{\lambda}}, \hat{\psi}] = \frac{\int \zeta_j \phi(\eta_j; 0, \hat{\psi}) \prod_i f(y_{ij} | \zeta_j; \hat{\boldsymbol{\beta}}, \hat{\boldsymbol{\lambda}}) d\zeta_j}{\ell_j(\hat{\boldsymbol{\beta}}, \hat{\boldsymbol{\lambda}}, \hat{\psi})}$$

- Posterior variance for unit j

$$\text{var}[\zeta_j | \mathbf{y}_j; \hat{\boldsymbol{\beta}}, \hat{\boldsymbol{\lambda}}, \hat{\psi}] = \frac{\int (\zeta_j)^2 \phi(\zeta_j; 0, \hat{\psi}) \prod_i f(y_{ij} | \zeta_j; \hat{\boldsymbol{\beta}}, \hat{\boldsymbol{\lambda}}) d\zeta_j}{\ell_j(\hat{\boldsymbol{\beta}}, \hat{\boldsymbol{\lambda}}, \hat{\psi})} - E[\zeta_j | \mathbf{y}_j; \hat{\boldsymbol{\beta}}, \hat{\boldsymbol{\lambda}}, \hat{\psi}]^2$$

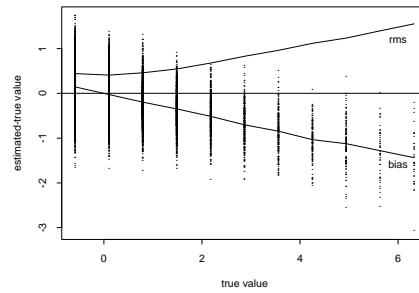
- The integrals are evaluated using adaptive quadrature

- NPMLE-based prediction:

$$\tilde{\zeta}_j^{\text{EB}} = E[\zeta_j | \mathbf{y}_j; \hat{\boldsymbol{\beta}}, \hat{\boldsymbol{\lambda}}, \hat{\boldsymbol{\pi}}_K, \hat{\boldsymbol{z}}_K] = \frac{\sum_{k=1}^K \hat{z}_k \hat{\pi}_k \prod_{i=1}^I f(y_{ij} | \zeta_j = \hat{z}_k; \hat{\boldsymbol{\beta}}, \hat{\boldsymbol{\lambda}}, \hat{\boldsymbol{\pi}}_K, \hat{\boldsymbol{z}}_K)}{\ell_j(\hat{\boldsymbol{\beta}}, \hat{\boldsymbol{\lambda}}, \hat{\boldsymbol{\pi}}_K, \hat{\boldsymbol{z}}_K)}$$

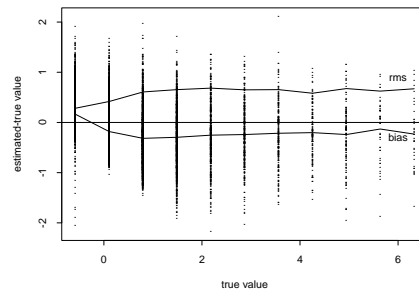
Performance: Prediction for skewed exposure

Normality assumed



Slide 33

NPMLE



Variations of latent variable prediction

1. Posterior variance:

$$\text{var}(\zeta_j | \mathbf{y}_j, \mathbf{x}_j, \hat{\boldsymbol{\theta}})$$

2. Marginal sampling variance:

$$\text{var}_{\mathbf{y}}(\tilde{\zeta}_j^{\text{EB}} | \mathbf{x}_j, \hat{\boldsymbol{\theta}})$$

'Diagnostic' variance in Goldstein (1995)

3. Conditional sampling variance:

$$\text{var}_{\mathbf{y}}(\tilde{\zeta}_j^{\text{EB}} | \zeta_j, \mathbf{x}_j, \hat{\boldsymbol{\theta}})$$

4. Prediction error variance (marginal):

$$\text{var}_{\mathbf{y}}(\tilde{\zeta}_j^{\text{EB}} - \zeta_j | \mathbf{x}_j, \hat{\boldsymbol{\theta}})$$

'Comparative' variance in Goldstein (1995)

Slide 34

Slide 35

Obtaining the standard errors of prediction

- Posterior variance obtained by numerical integration (as shown)
- Approximate expression for prediction error variance

$$\text{var}[\tilde{\zeta}_j^{\text{EB}} - \zeta_j | \mathbf{x}_j; \hat{\boldsymbol{\theta}}] \approx \text{var}[\zeta_j | \mathbf{y}_j, \mathbf{x}_j; \hat{\boldsymbol{\theta}}].$$

- Approximate expression for the marginal sampling variance

$$\text{var}[\zeta_j | \mathbf{x}_j; \hat{\boldsymbol{\theta}}] = E_{\mathbf{y}}[\text{var}[\zeta_j | \mathbf{y}_j, \mathbf{x}_j; \hat{\boldsymbol{\theta}}]] + \text{var}_{\mathbf{y}} \left[\underbrace{E[\zeta_j | \mathbf{y}_j, \mathbf{x}_j; \hat{\boldsymbol{\theta}}]}_{\tilde{\zeta}_j^{\text{EB}}} \right].$$

This can be rewritten as

$$\begin{aligned} \text{var}_{\mathbf{y}}[\tilde{\zeta}_j^{\text{EB}} | \mathbf{x}_j; \hat{\boldsymbol{\theta}}] &= \text{var}[\zeta_j | \mathbf{x}_j; \hat{\boldsymbol{\theta}}] - E_{\mathbf{y}}[\text{var}[\zeta_j | \mathbf{y}_j, \mathbf{x}_j; \hat{\boldsymbol{\theta}}]] \\ &\approx \hat{\psi} - \text{var}[\zeta_j | \mathbf{y}_j, \mathbf{x}_j; \hat{\boldsymbol{\theta}}]. \end{aligned}$$

Slide 36

IV. CONCLUSION

- Adaptive quadrature appears to work well in all situations
⇒ MQL/PQL and ordinary Gaussian quadrature obsolete?
- Estimation based on normality appears to be quite robust against misspecification of the latent variable distribution
- Prediction based on normality does not appear to be robust against misspecification of the latent variable distribution
⇒ Non-parametric maximum likelihood should be used for prediction of latent variables
- Suggested methodology for estimation and prediction is
 - applicable for entire GLLAMM framework (not just random intercept models!)
 - implemented in gllamm software running in STATA

Selected references from GLLAMM project

- GLLAMM framework:
 - *Generalized latent variable modeling: Multilevel, longitudinal and structural equation models*. Boca Raton, FL: Chapman & Hall/ CRC, to appear. (A.Skrondal & S.Rabe-Hesketh).
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 - “Multilevel logistic regression for polytomous data and rankings”. *Psychometrika*, 2003, in press (A.Skrondal & S.Rabe-Hesketh).
- glamm software:
 - *GLLAMM Manual*. London: Institute of Psychiatry, 2001. [128p]. (S.Rabe-Hesketh, A.Pickles & A.Skrondal).
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- Adaptive quadrature:
 - “Reliable estimation of generalized linear mixed models using adaptive quadrature”. *The Stata Journal*, 2: 1-21, 2002. (S.Rabe-Hesketh, A.Skrondal & A.Pickles).
 - “Maximum likelihood estimation of limited and discrete dependent variable models with nested random effects”. Submitted to *Journal of Econometrics*. (S.Rabe-Hesketh, A.Skrondal & A.Pickles).
- Non-parametric maximum likelihood:
 - “Correcting for covariate measurement error in generalised linear models using nonparametric maximum likelihood estimation”. Revised for *Statistical Modelling*. (S.Rabe-Hesketh, A.Pickles & A.Skrondal).

Slide 37